

CAME.COM

Sliding gate operator BXV series

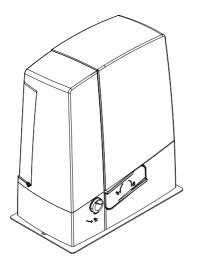


FA01004-EN







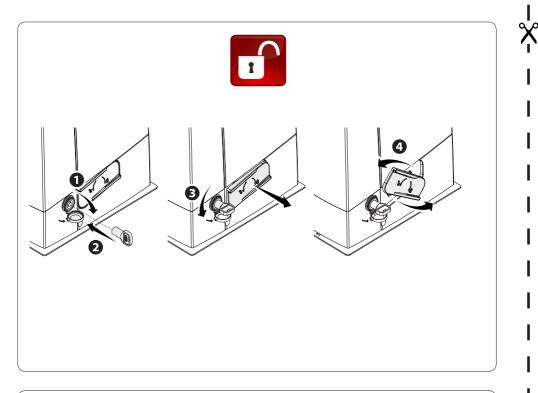


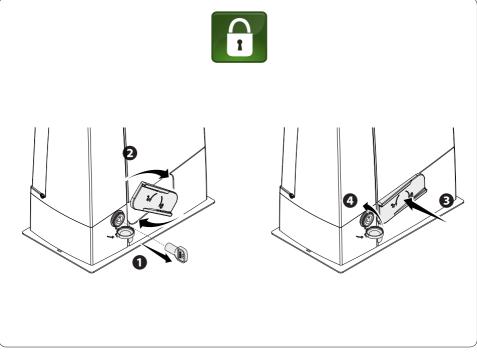
BXV04AGM

BXV04AGS/BXV06AGS/BXV08AGS/BXV10AGS BXV04RGS/BXV06RGS/BXV08RGS/BXV10RGS

INSTALLATION MANUAL







I

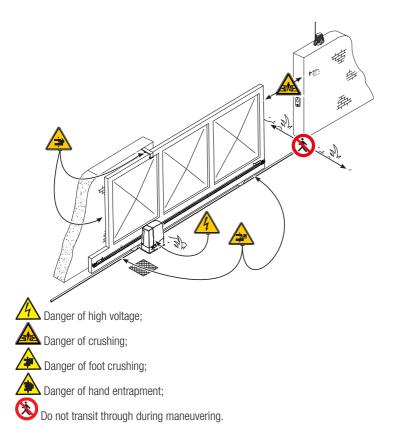
I

A WARNING! Important safety instructions. Followalloftheseinstructions.Improperinstallationcancauseseriousbodilyharm. Before continuing, also read the general precautions for users.

This product must only be used for its specifically intended purpose. Any other use is dangerous, Came S.P.A. is not liable for any damage caused by improper, wrongful and unreasonable use. • This manual's product is defined by machinery directive 2006/42/CE as "partly-completed machinery". Partly-completed machinery is a set that almost constitutes a machine, but which, alone, cannot ensure a clearly defined application. Partly-completed machinery is only destined to be incorporated or assembled to other machinery or other partly-completed machinery or apparatuses to build machinery that is regulated by Directive 2006/42/CE. The final installation must be compliant with European directive 2006/42/CE and current European reference standards. Given these considerations, all procedures stated in this manual must be exclusively performed by expert, qualified staff • The manufacturer declines any liability for using non-original products; which would result in warranty loss • Keep this manual inside the technical folder along with the manuals of all the other devices used for your automation system • Check that the operator's specified temperature range suits the locations where it will be installed • laving the cables, installation and testing must follow state-of-the-art procedures as dictated by regulations • If the power-supply cable is damaged, replace it immediately through the manufacturer or an authorized technical assistance center, or qualified staff, to prevent any risk • Make sure the mains power supply is disconnected during all installation procedures • The operator cannot be used with gates fitted with pedestrian gates, unless its operation can be activated only when the pedestrian gate is in safety position • Make sure that people are not entrapped between the gate's moving and fixed parts due to the gate's movement • Before installing the operator, check that the gate is in proper mechanical condition, that it is properly balanced and that it properly closes: if any of these conditions are not met, do not continue before having met all safety requirements • Make sure the gate is stable and the carriage function properly and are well-greased, and that it opens and closes smoothly • The quide rail must be well-fastened to the ground, entirely above the surface and free of any impediments to the gate's movement. • The rails of the upper guide must not cause any friction • Make sure that opening and closing limiters are fitted • Make sure the operator is installed onto a sturdy surface that is protected from any collisions • Make sure that mechanical stops are already installed. • If the operator is installed lower than 2.5 from the ground or from any other access level, fit protections and signs to prevent hazardous situations • Do not fit the operator upside down or onto elements that could yield under its weight If necessary, add reinforcements to the fastening points • do not install onto tilted gate leaves • check that no lawn watering devices spray the operator with water from the bottom up Any residual risks must be indicated clearly with proper signage affixed in visible areas. All of which must be explained to end users. • Suitably section off and demarcate the entire installation site to prevent unauthorized persons from entering the area, especially minors and children • Affix cautionary signs, such as, the gate plate, wherever needed and in plain sight. • Use proper protections to prevent mechanical hazards when people are loitering around the machinery's range of action, for example, to prevent finger crushing between the rack and pinion • The electrical cables must run through the cable glands and must not touch any heated parts, such as the motor, transformer, and so on) • Make sure you have set up a suitable dual pole cut off device along the power supply that is compliant with the installation rules. It should completely cut off the power supply according to category III surcharge conditions • All opening controls must be installed at least 1.85 m from the perimeter of the gate's working area, or where they cannot be reached from outside the gate •

All switches in maintained-action mode must be positioned so that the moving gates leaves, the transit areas and vehicle thru-ways are completely visible, and yet the switches must be also away from any moving parts. • Unless the action is key operated, the control devices must be fitted at, at least, 1.5 m from the ground and unreachable by any unauthorized persons. • To pass the collision force test use a suitable sensitive safety-edge. Install it properly and adjust as needed. • Before handing over to users, check that the system is compliant with the 2006/42/CE uniformed Machinery Directive. Make sure the settings on the operator are all suitable and that any safety and protection devices, and also the manual release, work properly. • Affix a permanent tag, that describes how to use the manual release mechanism, close to the mechanism. • Make sure to hand over to the end user, all operating manuals for the products that make up the final machinery.

- The next figure shows the main hazard points for people -



- Definition This symbol shows which parts to read carefully.
- \triangle This symbol shows which parts describe safety issues
- This symbol shows which parts to tell users about.

The measurements, unless otherwise stated, are in millimeters.

DESCRIPTION

Operator complete with control board, movement control and obstruction detection device and mechanical limit switches for sliding gates weighing up 1,000 Kg and measuring 20 m in length.

INTENDED USE

The operator is designed to power sliding gates in residential and apartment block settings. \square Do not install of use this device in any way, except as specified in this manual.

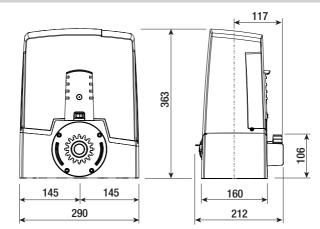
LIMITS TO USE

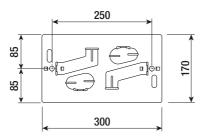
Туре	BXV04AGM BXV04AGS BXV04RGS	BXV06AGS BXV06RGS	BXV08AGS BXV08RGS	BXV10AGS BXV10RGS
Maximum gate-leaf length (m)	14	18	20	20
Maximum gate-leaf weight (kg)	400	600	800	1000
Pinion module	4	4	4	4

TECHNICAL DATA

Туре	BXV04AGM BXV04AGS BXV04RGS	BXV06AGS BXV06RGS	BXV08AGS BXV08RGS	BXV10AGS BXV10RGS
Protection rating (IP)		4	4	
Power supply (V - 50/60 Hz)		110/2	230 AC	
Input voltage motor (V)		24	DC	
Stand-by consumption (W)	5.5			
Stand-by consumption with the RGP1 (W) mo- dule		0.	5	
Maximum power (W)	170	270	4(00
Duty cycle		HEAVY-DUT	Y SERVICE	
Operating temperature (°C)	-20 to +55			
Thrust (N)	350	600	800	1000
Maneuvering speed (m/min)	1	2	1	1
Weight (Kg)	10	10.5	11.5	11.7

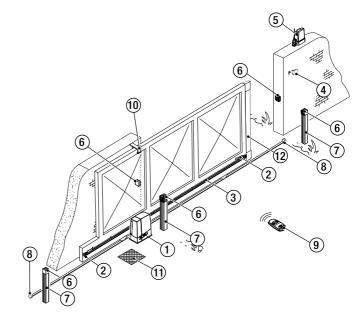
DIMENSIONS





STANDARD INSTALLATION

- 1. Operator
- 2. Limit-switch fins
- 3. Rack
- 4. Selector
- 5. Flashing light
- 6. Photocells
- 7. Photocell post
- 8. Mechanical gate stop
- 9. Transmitter
- 10. Slide guides
- 11. Junction pit
- 12. Sensitive safety-edge



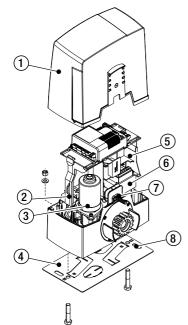
DESCRIPTION OF PARTS

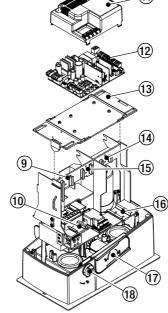
- 1. Cover
- Board-fitting support
 Gear motor
- 4. Anchoring plate
- 5. Housing for two emergency batteries
- 6. Transformer
- 7. Mechanical limit switch
- 8. Release cable threading hole
- 9. Housing for the RGP1 module
- 10. Housing for thermostat with heating rod
- 11.Protection card lid

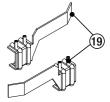
- 12. Control board
- 13. Control-board holder
- 14. Housing for the RLB battery charger
- 15. Housing for UR042 module
- 16. Housing for SMA and RGSM001 sensors
- 17. Release lever
- 18.Lock
- 19. Limit-switch fins

ΊÌ

20. Magnetic sensor (BXV04AGM only) 21. Magnetic limit-switch tabs (BXV04AGM only)











GENERAL INSTALLATION INDICATIONS

▲ Only skilled, qualified staff must install this product.

PRELIMINARY CHECKS

 \triangle Before beginning the installation, do the following:

• check that the upper slide-guides are friction-free;

• make sure there is are opening and closing mechanical gate stops;

• make sure that the point where the gear motor is fastened is protected from any impacts and that the surface is solid enough;

• set up suitable tubes and conduits for the electric cables to pass through, making sure they are protected from any mechanical damage.

CABLE TYPES AND MINIMUM SECTIONS

Connection	cable length		
Connection	< 20 m	20 < 30 m	
Input voltage for 230 V AC control board (1P+N+PE)	3G x 1.5 mm ²	3G x 2.5 mm ²	
Signaling devices	2 x 0.5 mm ²		
Command and control devices	2 x 0.5 mm ²		
Safety devices (photocells)	$(TX = 2 \times 0.5 \text{ mm}^2)$ $(RX = 2 \times 0.5 \text{ mm}^2)$		

When operating at 230 V and outdoors, use H05RN-F-type cables that are 60245 IEC 57 (IEC) compliant; whereas indoors, use H05W-F-type cables that are 60227 IEC 53 (IEC) compliant. For power supplies up to 48 V, you can use FROR 20-22 II-type cables that comply with EN 50267-2-1 (CEI).

Deconnect the antenna, use the RG58 (we suggest up to 5 m).

Propaired connection and CRP, use a UTP CAT5-type cable (up to 1,000 m long).

If cable lengths differ from those specified in the table, establish the cable sections depending on the actual power draw of the connected devices and according to the provisions of regulation CEI EN 60204-1.

Given For multiple, sequential loads along the same line, the dimensions on the table need to be recalculated according to the actual power draw and distances. For connecting products that are not contemplated in this manual, see the literature accompanying said products

INSTALLING

 Δ The following illustrations are mere examples. Consider that the space available where to fit the barrier and accessories will vary depending on the area where it is installed. It is up to the installer to find the most suitable solution.

CORRUGATED TUBE LAYING

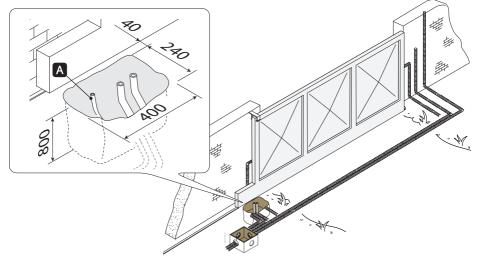
Dig a hole for the foundation frame.

Set up the corrugated tubes needed for the wiring coming out of the junction pit.

For connecting the gearmotor we suggest using a \emptyset 40 mm corrugated tube, whereas for the accessories we suggest \emptyset 25 mm tubes.

Set up a \emptyset 20 mm tube for running through the external release cable **A**.

I The number of tubes depends on the type of system and the accessories you are going to fit.

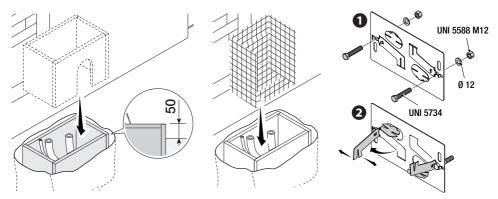


LAYING THE ANCHORING PLATE

Set up a foundation frame that is larger than the anchoring plate and sink it into the dug hole. The foundation frame must jut out by 50 mm above ground level.

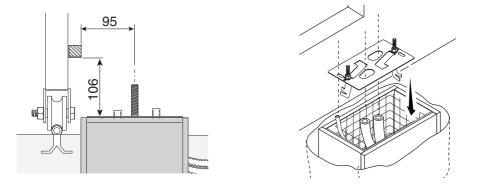
Fit an iron cage into the foundation frame to reinforce the concrete.

Fit the bolts into the anchoring plate and lock them using the washers and nuts. Remove the pre-shaped clamps using a screw driver or pliers.



If the rack is already there, place the anchoring plate, being careful to respect the measurements shown in the drawing.

Careful! The tubes must pass through their corresponding holes.

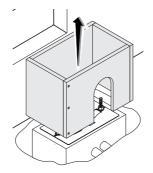


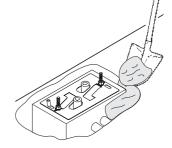
Fill the foundation frame with concrete. The plate must be perfectly level with the bolts which are entirely above surface.

Wait at least 24 hrs for the concrete to solidify.

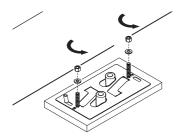
Remove the foundation frame and fill the hole with earth around the concrete block.

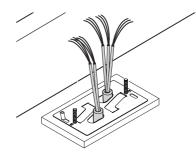






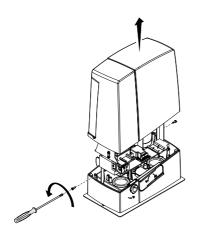
Remove the nut and washer from the bolts Fit the electric cables into the tubes so that they come out about 600 mm.

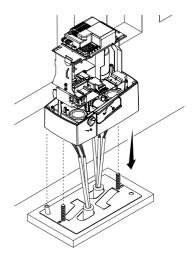




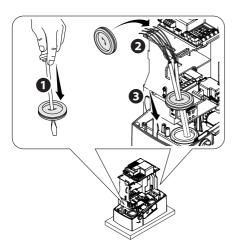
SETTING UP THE GEARMOTOR

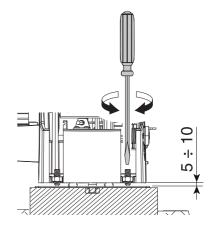
Remove the gearmotor cover by loosening the side screws. Place the gearmotor above the anchoring plate. Careful! The electric cables must pass under the gearmotor case.





Perforate the cable gland, pass the cables through and fit it into its corresponding housing. Raise the gearmotor by 5 to 10 mm from the plate by turning the threaded feet, to make room for further pinion and rack adjustments.



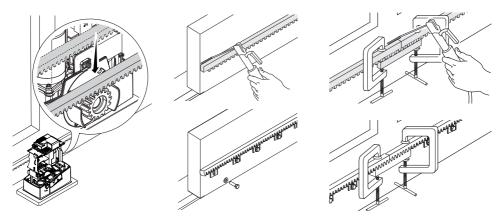


FASTENING THE RACK

📖 If the rack is already set up, the next step should be to adjust the rack-and-pinion coupling distance, otherwise, fasten it:

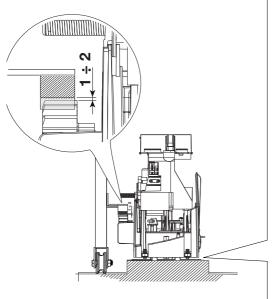
- release the gearmotor (see RELEASING THE GEARMOTOR paragraph);
- rest the rack above the gearmotor pinion;
- weld or fasten the rack to the gate along its entire length.

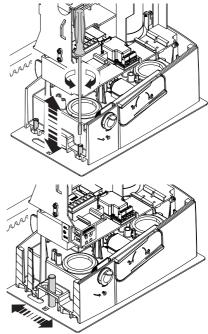
To assemble the rack modules, use an extra piece and rest it under the joint, then fasten it using two clamps.



ADJUSTING THE PINION-RACK COUPLING

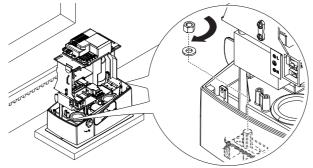
Manually open and close the gate and adjust the pinion-rack coupling distance using the threaded feet (vertical adjustment) and the holes (horizontal adjustment). This prevents the gate's weight from bearing down on the operator.





FASTENING THE GEAR MOTOR

Complete the adjusting, fasten the gearmotor to the plate using the washers and nuts.



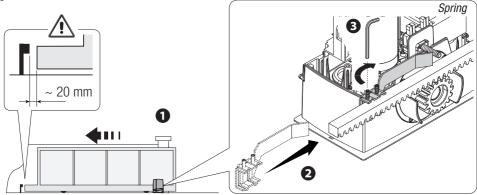
ESTABLISHING THE LIMIT-SWITCH POINTS

Mechanical limit-switches

For opening:

- open the gate **0**;

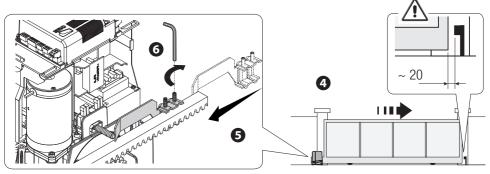
- fit the opening limit-switch fin onto the rack until the micro switch activates (spring) and fasten it using the grub screws **29**.



For closing:

- close the gate (1);

- fit the closing limit-switch fin into the rack until the micro-switch is activated (spring) and fasten it using the grub screws **66**.

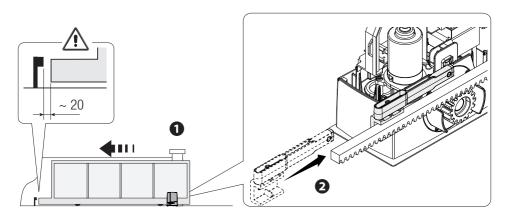


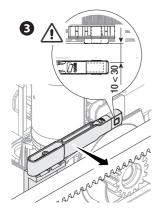
Limit-switch with magnetic sensor (BXV04AGM only)

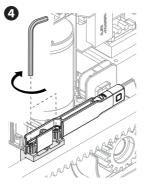
For opening:

- open the gate; 0

- switch, magnetic tab onto the rack while keeping the magnet - between 10 and 30 mm, away from the magnetic sensor; Θ

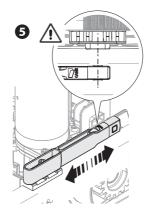


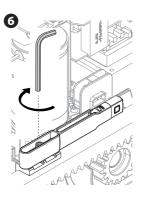




- Fasten the tab brace to the rack by using the headless screws; ④

place the tab magnet perpendicularly to the magnetic sensor;
tighten the screw to fasten the tab.

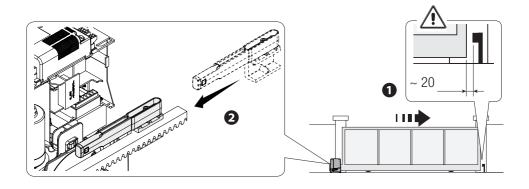


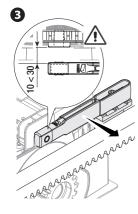


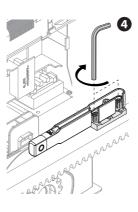
For closing:

- close the gate 0

- switch, magnetic tab onto the rack while keeping the magnet - between 10 and 30 mm, away from the magnetic sensor; 29

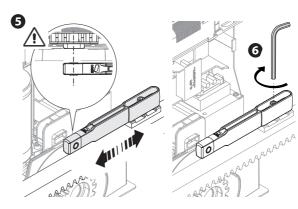






- Fasten the tab brace to the rack by using the headless screws; ④

place the tab magnet perpendicularly to the magnetic sensor;
tighten the screw to fasten the tab.





ELECTRICAL CONNECTIONS AND PROGRAMMING

 Δ Caution! Before working on the control panel, cut off the mains power supply and remove any batteries. Power supply to the control board and control devices : 24 V AC/ DC.

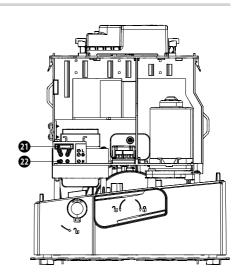
Functions on the input and output contacts, time adjustments and user-management settings are set and viewed on the control board's display.

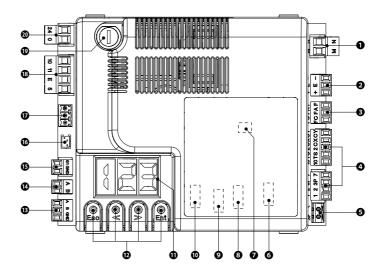
All wiring connections are quick-fuse protected.

Fuses	ZN7
LINE - Line	1.6 A-F (230 V) / 3.15 A-F (110 V)
ACCESSORIES - Accessories	2 A-F

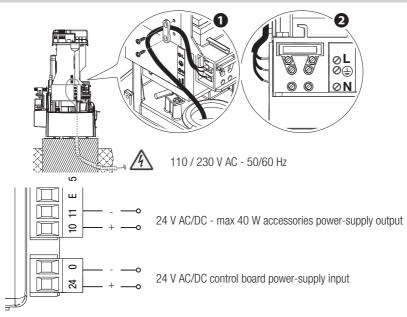
DESCRIPTION OF PARTS

- 1. Terminal for gearmotors
- 2. Terminals for encoders
- 3. Terminals for limit-switches
- 4. Command and safety devices terminals
- 5. Antenna terminal
- 6. AF card slot
- 7. Memory Roll card connector
- 8. R700/R800 board connector
- 9. RSE card slot
- 10. Connector for the RIOCN8WS card
- 11. Display
- 12. Programming buttons
- 13. Terminals for paired of CRP connection
- 14. Terminal board for keypad devices
- 15. Terminal board for transponder selector
- 16. Connector for the GSM module
- 17. Terminals for the RGP1 module
- 18. Terminals for signaling devices
- 19. Accessories fuse
- 20. Terminals for powering the control board
- 21. Line fuse
- 22. Power supply terminal board

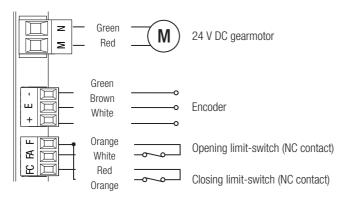




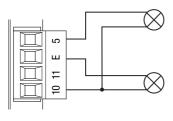
INPUT VOLTAGE



FACTORY WIRING



SIGNALING DEVICES

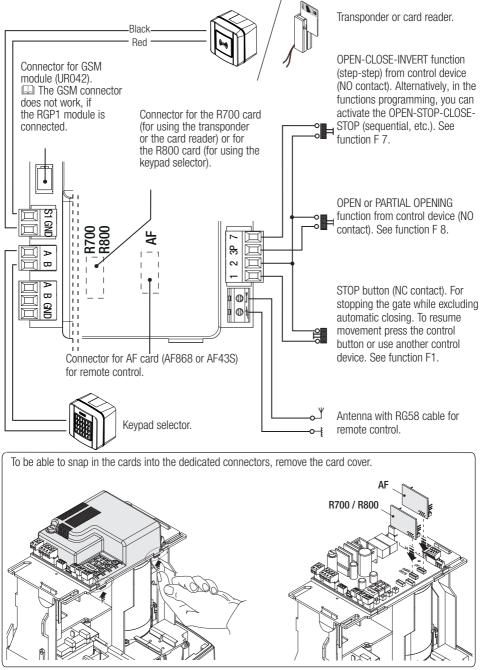


Gate open signaling output (Contact rated for: 24 V AC/DC - 3 W max.). See function F 10.

Either flashing light or cycle light connection output (Contact rated for: 24 V AC/DC - 25 W max.). See function F 18.

COMMAND AND CONTROL DEVICES

WARNING! For the system to work properly, before fitting any plug-in card, such as the AF or R800 one, you MUST CUT OFF THE MAINS POWER SUPPLY and, if present, disconnect any batteries.



SAFETY DEVICES

Photocells

Configure contact CX or CY (NC), safety input for photocells.

See CX input functions (Function F2) or CY (Function F3) in:

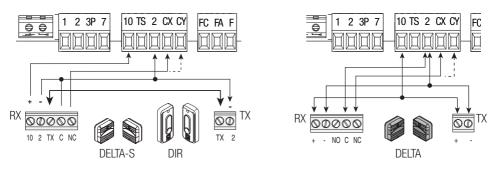
- C1 reopening during closing. When the gate is closing, opening the contact triggers the inversion of movement until the gate is fully open again;

- C2 close back up during opening. When the gate is opening, opening the contact triggers the inversion of movement until the gate is completely closed.

- C3 partial stop. Stopping of the gate, if it is moving, with consequent automatic closing (if the automatic closing function has been entered);

- C4 obstruction wait. Stopping of the gate, if it is moving, which resumes movement once the obstruction is removed.

If contacts CX and CY are not used they should be deactivated during programming.



Sensitive Safety Edges

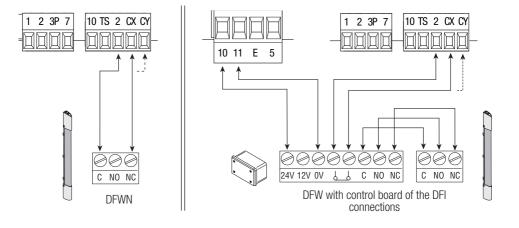
Configure contact CX or CY (NC), safety input for sensitive safety-edges.

See CX input functions (Function F2) or CY (Function F3) in:

- C7 reopening during closing. When the gate is closing, opening the contact triggers the inversion of movement until the gate is fully open again;

- C8 reclosing during opening. When the gate is opening, opening the contact triggers the inversion of movement until the gate is fully closed.

If contacts CX and CY are not used they should be deactivated during programming.

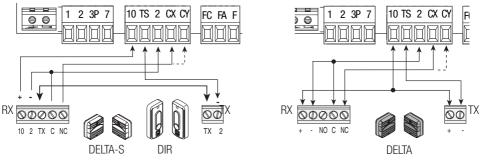


Connecting the safety devices (i.e. the safety test)

At each opening and closing command, the control board checks the efficacy of the safety devices (such as, photocells).

Any malfunction inhibits any command and is signaled on display E4.

Enable function F 5 in programming.



RIO WIRELESS DEVICES

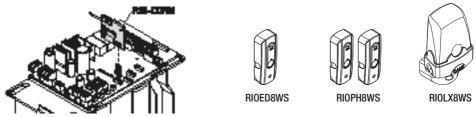
Plug the RIOCN8WS card into its corresponding connector on the control board.

Set the function to be associated to the wireless device (F65, F66, F67 e F68).

Configure the RIOED8WS, RIOPH8WS and RIOLX8WS wireless accessories by following the indications shown in the folder enclosed with each accessory.

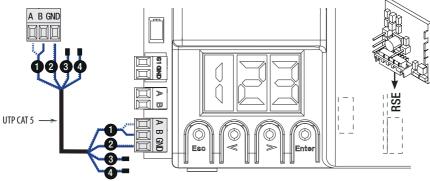
If the devices are not configured with the RIOCN8WS card, the display will read out E18.

 \triangle If there are any radio-frequency disturbances to the system, the wireless system will inhibit the normal operation of the operator, and this error will show up on the display as E17.



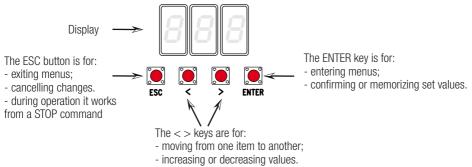
CONNECTION FOR PAIRED OPERATION AND FOR CRP (CAME REMOTE PROTOCOL)

See the PAIRED CONNECTION WITH SINGLE CONTROL chapter.



Fit the RSE card.

DESCRIPTION OF PROGRAMMING COMMANDS



- after a travel calibration they allow an OPEN or CLOSE command

FUNCTIONS MENU

- □ IMPORTANT! Start programming by first performing the following: MOTOR-TYPE SETTING (A1), OPENING DIRECTION (F54), TOTAL STOP (F1) and TRAVEL CALIBRATION (A3)
- $\ensuremath{\vartriangle}$ Only program functions when the operator is stopped.
- \square You can memorize up to 25 maximum users.
- \square When the menu is active, the system cannot be used.

F1 Total stop [1-2] the control device. The safety device is inserted into [1-2]. <i>OFF</i> = Deactivated (default) / ON = Activated F2 Input [2-CX] NC input - Can associate: C1 = reopening during closing by photocells, C2 = reclosing during opening by photocells, C3 = partial stop, C4 = obstruction wait, C7 = reopening during closing by sensitive safety-edges, C8 = reclosing during opening by photocells, C2 = reclosing during opening by photocells, C3 = partial stop, C4 = obstruction wait, C7 = reopening during closing by sensitive safety-edges, C3 = partial stop, C4 = obstruction wait, C7 = reopening during closing by sensitive safety-edges, C8 = reclosing during opening by sensitive safety-edges, C3 = partial stop, C4 = obstruction wait, C7 = reopening during closing by sensitive safety-edges, C3 = partial stop, C4 = obstruction wait, C7 = reopening during closing by sensitive safety-edges, C8 = reclosing during opening by sensitive safety-edges. F3 Input [2-CY] NC input - Can associate: C1 = reopening during closing by photocells, C2 = reclosing during closing by sensitive safety-edges, C3 = partial stop, C4 = obstruction wait, C7 = reopening during closing by sensitive safety-edges, C3 = partial stop, C4 = obstruction wait, C7 = reopening during closing by sensitive safety-edges, C3 = partial stop, C4 = obstruction wait, C7 = reopening during closing by sensitive safety-edges, C3 = reclosing during opening by sensitive safety-edges, C3 = partial stop, C4 = obstruction wait, C7 = reopening during closing by term safety edges, C3 = reclosing during opening by sensitive			
F2Input [2-CX]NC input – Can associate: C1 = reopening during closing by photocells, C2 = reclosing during opening by photocells, C3 = partial stop, C4 = obstruction wait, C7 = reopening during closing by sensitive safety-edges, C8 = reclosing during opening by sensitive safety-edges.F3Input [2-CY]NC input – Can associate: C1 = reopening during closing by photocells, C2 = reclosing during opening by photocells, C3 = partial stop, C4 = obstruction wait, C7 = reopening during closing by sensitive safety-edges, C8 = reclosing by photocells, C2 = reclosing during closing by sensitive safety-edges, C8 = reclosing during opening by sensitive safety-edges.F3Input [2-CY]NC input – Can associate: C1 = reopening during closing by photocells, C2 = reclosing during closing by sensitive safety-edges, C8 = reclosing during opening by sensitive safety-edges.F5Safety testOFF = Deactivated (default) / C1 / C2 / C3 / C4 / C7 / C8F5Safety testAfter every opening or closing command, the board will check whether the photocells are working properly. 	F1	Total stop [1-2]	NC input – Gate stop that excludes any automatic closing; to resume movement, use the control device. The safety device is inserted into $[1-2]$.
F2Input [2-CX]during opening by photocells, C3 = partial stop, C4 = obstruction wait, C7 = reopening during closing by sensitive safety-edges, C8 = reclosing during opening by sensitive safety-edges.F3Input [2-CY] $OFF = Deactivated (default) / C1 / C2 / C3 / C4 / C7 / C8$ F3Input [2-CY]NC input - Can associate: C1 = reopening during closing by photocells, C2 = reclosing during opening by photocells, C3 = partial stop, C4 = obstruction wait, C7 = reopening during closing by sensitive safety-edges, C8 = reclosing during opening by sensitive safety-edges.F3Input [2-CY]NC input - Can associate: C1 = reopening during closing by photocells, C2 = reclosing during closing by sensitive safety-edges, C8 = reclosing during opening by sensitive safety-edges.F5Safety testAfter every opening or closing command, the board will check whether the photocells are working properly. 			OFF = Deactivated (default) / ON = Activated
F3 Input [2-CY] during opening by photocells, C3 = partial stop, C4 = obstruction wait, C7 = reopening during closing by sensitive safety-edges, C8 = reclosing during opening by sensitive safety-edges. F5 Safety test OFF = Deactivated (default) / C1 / C2 / C3 / C4 / C7 / C8 F5 Safety test After every opening or closing command, the board will check whether the photocells are working properly. □ The safety test is always active for wireless devices. 0= Deactivated (default) / 1=CX / 2=CY / 4=CX+CY F6 Maintained action 0= Deactivated (default) / 1= Activated	F2 Input [2-CX]		
F5 Safety test After every opening or closing command, the board will check whether the photocells are working properly. Image: F5 Safety test The safety test is always active for wireless devices. 0= Deactivated (default) / 1=CX / 2=CY / 4=CX+CY F6 Maintained action The barrier opens and closes by keeping a button pressed. Opening button on contact 2-3 and closing button on contact 2-4. All other control devices, even radio-based ones, are excluded. 0= Deactivated (default) / 1= Activated	F3	Input [2-CY]	
F5 Safety test are working properly. □ The safety test is always active for wireless devices. <i>D</i> = Deactivated (default) / 1=CX / 2=CY / 4=CX+CY F6 Maintained action The barrier opens and closes by keeping a button pressed. Opening button on contact 2-3 and closing button on contact 2-4. All other control devices, even radio-based ones, are excluded. <i>D</i> = Deactivated (default) / 1 = Activated			OFF = Deactivated (default) / C1 / C2 / C3 / C4 / C7 / C8
F6 Maintained action The barrier opens and closes by keeping a button pressed. Opening button on contact 2-3 and closing button on contact 2-4. All other control devices, even radio-based ones, are excluded. 0= Deactivated (default) / 1= Activated	F5	Safety test	
F6 Maintained action 2-3 and closing button on contact 2-4. All other control devices, even radio-based ones, are excluded. 0= Deactivated (default) / 1= Activated			0 = Deactivated (default) / 1 =CX / 2 =CY / 4 =CX+CY
	F6		The barrier opens and closes by keeping a button pressed. Opening button on contact 2-3 and closing button on contact 2-4. All other control devices, even radio-based ones, are excluded.
From the control device connected to 2-7, it performs the (open-close-invert) step-step,			0= Deactivated (default) / 1= Activated
F7 Command [2-7] (open-stop-close-stop), sequential, open or close command.	F7	Command [2-7]	From the control device connected to 2-7, it performs the (open-close-invert) step-step, (open-stop-close-stop), sequential, open or close command.
0 = Step-step (default) / 1 = Sequential / 2 = Open / 3 = Close			0 = Step-step (default) / 1 = Sequential / 2 = Open / 3 = Close

F8	Command [2-3P]	From the control device connected to 2-3P, it performs a partial (1) or total opening (2) of the gate. The partial opening time is adjusted on function F 71. 1 = partial opening / 2 = Open
F9	Obstruction detection with motor stopped	With the gate closed, opened or totally stopped, the gearmotor stays idle if the safety devices, that is, photocells or sensitive safety-edges detect an obstruction. OFF = Deactivated (default) / $ON = Activated$
F10	Gate open signaling output	It signals the gate status. The signal device is connected to contact 10-5. <i>O</i> = <i>lit when gate is open or moving (default)</i> / <i>1</i> = <i>during openings it flashes</i> <i>intermittently each half second, and during closings it flashes intermittently</i> <i>each second.</i> <i>It stays on steadily when the barrier is open, off or when it s closed.</i>
F11	Encoder	Managing slow-downs, obstruction detections and sensitivity. <i>OFF</i> = <i>Deactivated</i> / <i>ON</i> = <i>Activated</i> (<i>default</i>)
F12	Soft Start	With each opening and closing command, the gate starts moving slowly for a few seconds. OFF = Deactivated (default) / $ON = Activated$
F14	Sensor type selection	Setting the type of accessory for controlling the operator. 0 = command with transponder sensor or magnetic card reader / 1 = command with keypad selector (default).
F18	Additional light	Output on contact 10-E. Flashing light: it flashes during the gate's opening and closing phases. Cycle: outdoor lamp for extra lighting in the driveway. It stays lit from when the gate starts opening to when it closes, including the waiting time prior to automatic closing (only with with TCA activated).
F19	Automatic Closing Time	0 = Flashing light (default) / 1 = Cycle The automatic-closing wait starts when the opening limit switch point is reached and can be set to between 1 and 180 seconds. The automatic closing does not work if any of the safety devices trigger when an obstruction is detected, or after a total stop, or during a power outage. 0FF = Deactivated (default) / 1 = 1 second / / 180 = 180 seconds
F20	Automatic closing time after partial opening	The wait before the automatic closing starts after a partial opening command for an adjustable time of between 1 s and 180 s. The automatic closing does not work if any of the safety devices trigger when an obstruction is detected, or after a total stop, or during a power outage. The F19 function must not be activated. $OFF = Deactivated / 1 = 1 \ seconds / \dots / 10 = seconds \ (default) / \dots / 180 = 180 \ seconds$
F21	Pre-flashing time	Adjusting the pre-flashing time for the flashing light connected to 10-E before each maneuver. The flashing time is adjustable from one to ten seconds. OFF = Deactivated (default) / 1 = 1 seconds / / 10 = 10 seconds
F28Gate travel speedSetting the gate's opening and closing speed 60 = Minimum speed / / 100 = Maximu Setting the gate's opening and closing slow-F30Slow-down		Setting the gate's opening and closing speeds, calculated as a percentage. 60 = Minimum speed / / 100 = Maximum speed (default)
		Setting the gate's opening and closing slow-down speed, calculated as a percentage. 10 = Minimum speed / / 50 = Maximum speed (default)
F34	Travel sensitivity	Adjusting obstruction detection sensitivity during gate-leaf travel. 10 = maximum sensitivity / / 100 = minimum sensitivity (default)

F35	Slow-down sensitivity	Adjusting obstruction detection sensitivity during slow-down. 10 = maximum sensitivity / / 100 = minimum sensitivity (default)
F36	Adjusting the partial opening	Adjustment as a percentage of total travel, during gate opening. This function appears only is the Encoder function is activated. 10 = 10% of the gate travel (default) / / $80 = 80%$ of the door travel
F37	Opening slow- down point	Percentage adjustment of the total door travel, of the opening slow-down starting point. This function appears only is the Encoder function is activated. 10 = 10% of the gate-leaf travel / / $25 = 25%$ of the gate-leaf travel (default) / / $60 = 60%$ of the gate-leaf travel
F38	Closing slow- down point	Percentage adjustment of the total door travel, from the closing slow-down starting point. This function appears only is the Encoder function is activated. 10 = 10% of the gate-leaf travel / / $25 = 25%$ of the gate-leaf travel (default) / / $60 = 60%$ of the gate-leaf travel
F49	Managing the serial connection	To enable the paired operating mode or the CRP (Came Remote Protocol). 0 = Deactivated (default) / 1 = Paired / 3 = CRP
F50	Saving data	Saving users and settings saved in the Memory Roll. This function only appears if a Memory Roll has been plugged into the control board.
F51	Reading of data	 <i>O</i> = Deactivated (default) / 1 = Activated Uploading data saved in the Memory Roll. This function only appears if a Memory Roll has been plugged into the control board. <i>O</i> = Deactivated (default) / 1 = Activated
Transferring F52 parameters in paired mode		Uploading settings from Master to Slave. This appears only if function F49 is set to Paired. OFF = Deactivated (default) / ON = Activated
F54	Opening direction	For setting the gate opening direction. OFF = Opening left (default) / ON = Opening right
F56	Peripheral number	To set the peripheral's number from 1 to 255 for each control board when you have a system with several operators. 1> 255
F63	Changing COM speed	For setting the communication speed used in the CRP (Came Remote Protocol) connection system. 0 = 1200 Baud / 1 = 2400 Baud / 2 = 4800 Baud / 3 = 9600 Baud / 4 = 14400 Baud / 5 = 19200 Baud / 6 = 38400 Baud (default) / 7 = 57600 Baud / 8 = 115200 Baud
F65	Wireless input RIOED8WS [T1]	Wireless safety device (RIOED8WS) associated to a function of choice among those available: $PO = TOTAL$ STOP, $P7 =$ reopening during closing, $P8 =$ reclosing during opening.For programming, see the instructions that come with the accessory.Im This function only appears if the RIOCN8WS card is plugged into the control board. $OFF = Deactivated$ (default) / P0 / P7 / P8

F66Wireless input RIOED8WS [72]Wireless safety device (RIOED8WS) associated to a function of choice among these available: P0 = TOTAL STOP, P7 = reopening during closing, P8 = reclosing during opening. For programming, see the instructions that come with the accessory. His function only appears if the RIOCN8WS card is plugged into the control board. OFF = Deactivated (default) / P0 / P7 / P8F67Wireless input RIOPH8WS [71]RioPH8WS [71] This function only appears if the RIOCN8WS card is plugged into the control board. OFF = Deactivated (default) / P2 marked areas / P3 / P4F68Wireless input RIOPH8WS [72]RioPH8WS [73] This function only appears if the RIOCN8WS card is plugged into the control board. OFF = Deactivated / P1 (default) / P2 marked areas / P3 / P4F68Wireless input RioPH8WS [72]RioPH8WS [73] This function only appears if the RIOCN8WS card is plugged into the control board. OFF = Deactivated / P1 (default) / P2 marked areas / P3 / P4F71Partial opening timeRioDPH8WS [73] This function only appears if the RIOCN8WS card is plugged into the control board. OFF = Deactivated / P1 (default) / P2 marked areas / P3 / P4F71Partial opening timeRioDPH8WS [74] This function only appears if the Encoder function is deactivated. S = 5 seconds / / 40 = 40 secondsF11Entering uses: USERS WITH ASSOCIATED COMMAND paragraph). I = Step-step command (open-stop-close) stop) / 3 = Open only command / 4 = PF31Deleting all users: D = Deactivated / ON = ActivatedF42Deleting all users: D = Deactivated / ON = ActivatedF43Deleting all users: D = Deactivated / ON = ActivatedF44Deleting					
 F67 Wireless input RioPHaWS [T1] Grorogramming, see the instructions that come with the accessory. Fis function only appears if the RioCMSWS card is plugged into the control board. <i>OFF = Deactivated / P1 (default) / P2 marked areas / P3 / P4</i> F68 Wireless input RioPHaWS [T2] F69 Partial opening important only appears if the RioCMSWS card is plugged into the control board. <i>OFF = Deactivated / P1 (default) / P2 marked areas / P3 / P4</i> F71 Partial opening important only appears if the RioCMSWS card is plugged into the control board. <i>OFF = Deactivated / P1 (default) / P2 marked areas / P3 / P4</i> F71 Partial opening important on the button connected to 2-3P, the gate opens for an adjustable time of between five seconds and 40 seconds. GL This function only appears if the Encoder function is deactivated. <i>5 = 5 seconds / / 40 = 40 seconds</i> Entering users U1 Entering users Deleting users Deleting users Deleting users Deleting users Deleting aluesrs. <i>0 = Deactivated (default) / 1 = Delete</i> Sec the thype of transmitter and command / <i>4 P</i> artial command (open-stop-close-stop) / <i>3 = Open only command / 4 = P</i> artial command (open-stop-close-stop) / <i>3 = Open only command / 4 = P</i> artial command Deleting users Deleting aluesrs. <i>0 = Deactivated (default) / 1 = Delete</i> Set the type of transmitter radio coding all saved transmitter are automatically deleted. Gate-swing Gate-swing Gate-swing Gate-swing Automatic calibration of the gate-leaf swing (see the CALIBRATING SWING paragraph). <i>1 = Aloo kg / 2 = 600 kg / 3 = 800 kg / 4 = 1000 kg</i> Ai Motor type <i>1 = 400 kg / 2 = 600 kg / 3 = 800 kg / 4 = 1000 kg</i> Ai Maneuver count <i>OFF = Deactivated / N = Activated</i> <i>Automatic calibration of the gate-leaf swing (see the CALIBRATING SWING paragr</i>	F66		available: P0 = TOTAL STOP, P7 = reopening during closing, P8 = reclosing during opening. For programming, see the instructions that come with the accessory.		
 F68 Wireless input RioPH8WS [T2] F67 RioPH8WS [T2] Partial opening time F71 Partial opening t	F67		during closing; P2 = reclosing during opening; P3 = partial stop; P4 = obstruction wait. For programming, see the instructions that come with the accessory. \square This function only appears if the RIOCN8WS card is plugged into the control board.		
F68Wireless input RIOPH8WS [TZ]during closing; P2 = reclosing during opening; P3 = partial stop; P4 = obstruction wait. For programming, see the instructions that come with the accessory. This function only appears if the RIOCN8WS card is plugged into the control board. OFF = Deactivated / P1 (default) / P2 marked areas / P3 / P4F71Partial opening timeAfter an opening command from the button connected to 2-3P, the gate opens for an adjustable time of between five seconds and 40 seconds. This function only appears if the EncOder function is deactivated. $5 = 5 seconds / / 40 = 40 seconds$ U1Entering usersU520 users and associating to each one a function of choice among those included. This must be done via transmitter or other control device (see "ENTERING 					
F71Partial opening timeAfter an opening command from the button connected to 2-3P, the gate opens for an adjustable time of between five seconds and 40 seconds. 	F68	Wireless input RIOPH8WS [T2]	during closing; $P2 =$ reclosing during opening; $P3 =$ partial stop; $P4 =$ obstruction wait. For programming, see the instructions that come with the accessory. \square This function only appears if the RIOCN8WS card is plugged into the control board.		
F71Partial opening timeadjustable time of between five seconds and 40 seconds. 			OFF = Deactivated / P1 (default) / P2 marked areas / P3 / P4		
U1Entering usersEntering up to 250 users and associating to each one a function of choice among those included. This must be done via transmitter or other control device (see "ENTERING USERS WITH ASSOCIATED COMMAND paragraph). $1 = Step-step command (open-close) / 2 = Sequential command (open-stop-close-stop) / 3 = Open only command / 4 = Partial commandU2Deleting usersDeleting a single userOFF = Deactivated / ON = ActivatedU3Deleting usersDeleting all users.0 = Deactivated (default) / 1 = DeleteU4Decodingthe radio-frequency codeSelect the type of transmitter radio coding that you wish to save on the control board.\triangle When you select a radio coding, all saved transmitter are automatically deleted.\square TWIN's coding lets you save multiple users with the same key (Key block).1 = all series (default) / 2 = only Rolling Code series / 3 = only TWIN seriesA1Motor typeTo set the gaermotor depending on the gate's weight.1 = 400 \text{ kg } / 2 = 600 \text{ kg } / 3 = 800 \text{ kg } / 4 = 1000 \text{ kg}A3Gate-swingparametersCation! The default settings are restored and the travel calibration deleted.OFF = Deactivated / ON = ActivatedA4ResettingparametersOFF = Deactivated / ON = ActivatedA5ManeuvercountFor viewing the number of maneuvers; 999 = 99,900 maneuvers; 010 = 1,000maneuvers; 100 = 10,000 maneuvers; 999 = 99,900 maneuvers; CSI = maintenancejob).A6Adjusting themotor torqueFor adjusting the motor torque from 1 (minimum) to 5 (maximum).1/2/3/4/5$	F71		adjustable time of between five seconds and 40 seconds.		
U1Entering usersincluded. This must be done via transmitter or other control device (see "ENTERING USERS WITH ASSOCIATED COMMAND paragraph). $1 = Step-step command (open-close) / 2 = Sequential command (open-stop-close-stop) / 3 = Open only command / 4 = Partial commandU2Deleting usersDeleting usersU3Deleting usersOFF = Deactivated / ON = ActivatedU4Decodingthe radio-frequency codeDeleting a single users.0 = Deactivated (default) / 1 = DeleteU4Select the type of transmitter radio coding that you wish to save on the control board.\triangle When you select a radio coding, all saved transmitter are automatically deleted.\square TWIN's coding lets you save multiple users with the same key (Key block).1 = all series (default) / 2 = only Rolling Code series /3 = only TWIN seriesTo set the gearmotor depending on the gate is weight.1 = 400 \text{ kg }/ 2 = 600 \text{ kg }/ 3 = 800 \text{ kg }/ 4 = 1000 \text{ kg}A3Gate-swingcalibrationOFF = Deactivated / ON = ActivatedA4ResettingparametersOFF = Deactivated / ON = ActivatedA4ResettingparametersOFF = Deactivated / ON = ActivatedA5ManeuvercountOFF = Deactivated / ON = ActivatedA6Adjusting themotor torqueFor viewing the number of maneuvers made (001 = 100 maneuvers; CSI = maintenancejob).A6Adjusting themotor torqueFor adjusting the motor torque from 1 (minimum) to 5 (maximum).1/2/3/4/5$			5 = 5 seconds / / 40 = 40 seconds		
stop) / 3 = Open only command / 4 = Partial commandU2Deleting users $OFF = Deactivated / ON = Activated$ U3Deleting users $OFF = Deactivated / ON = Activated$ U4Decoding the radio- frequency codeDeleting lusers. 0 = Deactivated (default) / 1 = DeleteU4Select the type of transmitter radio coding that you wish to save on the control board. \triangle When you select a radio coding, all saved transmitter are automatically deleted. \square TWIN's coding lets you save multiple users with the same key (Key block). $1 = all series (default) / 2 = only Rolling Code series /3 = only TWIN series$ A1Motor typeTo set the gearmotor depending on the gate's weight. $1 = 400 \text{ kg }/2 = 600 \text{ kg }/3 = 800 \text{ kg }/4 = 1000 \text{ kg}$ A3Gate-swing calibrationAutomatic calibration of the gate-leaf swing (see the CALIBRATING SWING paragraph). $OFF = Deactivated / ON = Activated$ A4Resetting parametersCaution! The default settings are restored and the travel calibration deleted. $OFF = Deactivated / ON = Activated$ A5Maneuver countFor viewing the number of maneuvers; $999 = 99,900$ maneuvers; $CSI =$ maintenance job).A6Adjusting the motor torqueFor adjusting the motor torque from 1 (minimum) to 5 (maximum). $1/2/3/4/5$	U1		included. This must be done via transmitter or other control device (see "ENTERING		
U2Deleting users $OFF = Deactivated / ON = Activated$ U3Deleting users $Deleting all users.$ U4 $Decoding$ the radio- frequency codeSelect the type of transmitter radio coding that you wish to save on the control board. Δ When you select a radio coding, all saved transmitter are automatically deleted. \square TWIN's coding lets you save multiple users with the same key (Key block). $1 = all series (default) / 2 = only Rolling Code series /3 = only TWIN series$ A1Motor typeTo set the gearmotor depending on the gate's weight. $1 = 400 \ kg / 2 = 600 \ kg / 3 = 800 \ kg / 4 = 1000 \ kg$ A3Gate-swing calibrationAutomatic calibration of the gate-leaf swing (see the CALIBRATING SWING paragraph). $OFF = Deactivated / ON = Activated$ A4Resetting parametersCaution! The default settings are restored and the travel calibration deleted. $OFF = Deactivated / ON = Activated$ A5Maneuver countFor viewing the number of maneuvers; $999 = 99,900$ maneuvers; $CSI =$ maintenance job).A6Adjusting the motor torqueFor adjusting the motor torque from 1 (minimum) to 5 (maximum). $1/2/3/4/5$					
U3Deleting usersOFF = Deactivated / ON = Activated U4Decoding the radio- frequency codeDeleting all users. $0 = Deactivated (default) / 1 = Delete$ U4Decoding the radio- frequency codeSelect the type of transmitter radio coding, all saved transmitter are automatically deleted. \square TWIN's coding lets you save multiple users with the same key (Key block). $1 = all series (default) / 2 = only Rolling Code series /3 = only TWIN series$ A1Motor typeTo set the gearmotor depending on the gate's weight. $1 = 400 \text{ kg } / 2 = 600 \text{ kg } / 3 = 800 \text{ kg } / 4 = 1000 \text{ kg}$ A3Gate-swing calibrationAutomatic calibration of the gate-leaf swing (see the CALIBRATING SWING paragraph). $OFF = Deactivated / ON = Activated$ A4Resetting parametersCaution! The default settings are restored and the travel calibration deleted. $OFF = Deactivated / ON = Activated$ A5Maneuver countFor viewing the number of maneuvers; $999 = 99,900$ maneuvers; $CSI =$ maintenance job).A6Adjusting the motor torqueFor adjusting the motor torque from 1 (minimum) to 5 (maximum). $1/2/3/4/5$	112		Deleting a single user		
03 Deleting users 0 = Deactivated (default) / 1 = Delete 04 Decoding the radio- frequency code Select the type of transmitter radio coding that you wish to save on the control board.	<i>OFF</i> = Deactivated / <i>ON</i> = Activated		OFF = Deactivated / ON = Activated		
U4Decoding the radio- frequency codeSelect the type of transmitter radio coding, all saved transmitter are automatically deleted. \triangle When you select a radio coding, all saved transmitter are automatically deleted. \triangle When you select a radio coding, all saved transmitter are automatically deleted. \triangle When you select a radio coding, all saved transmitter are automatically deleted. \triangle When you select a radio coding, all saved transmitter are automatically deleted. 	113	Deleting users	Deleting all users.		
U4Decoding the radio- frequency code \triangle When you select a radio coding, all saved transmitter are automatically deleted. \square TWIN's coding lets you save multiple users with the same key (Key block). $1 = all series (default) / 2 = only Rolling Code series /3 = only TWIN series$ A1Motor typeTo set the gearmotor depending on the gate's weight. $1 = 400 \text{ kg }/2 = 600 \text{ kg }/3 = 800 \text{ kg }/4 = 1000 \text{ kg}$ A3Gate-swing calibrationAutomatic calibration of the gate-leaf swing (see the CALIBRATING SWING paragraph). $OFF = Deactivated / ON = Activated$ A4Resetting parametersCaution! The default settings are restored and the travel calibration deleted. $OFF = Deactivated / ON = Activated$ A5Maneuver countFor viewing the number of maneuvers; $999 = 99,900$ maneuvers; $CSI =$ maintenance job).A6Adjusting the motor torqueFor adjusting the motor torque from 1 (minimum) to 5 (maximum). $1/2/3/4/5$	00	Deleting users	0 = Deactivated (default) / 1 = Delete		
A1Motor typeTo set the gearmotor depending on the gate's weight. $1 = 400 \ kg/2 = 600 \ kg/3 = 800 \ kg/4 = 1000 \ kg$ A3Gate-swing calibrationAutomatic calibration of the gate-leaf swing (see the CALIBRATING SWING paragraph). $OFF = Deactivated / ON = Activated$ A4Resetting parametersCaution! The default settings are restored and the travel calibration deleted. $OFF = Deactivated / ON = Activated$ A5Maneuver countFor viewing the number of maneuvers; $999 = 99,900$ maneuvers; $CSI =$ maintenance job).A6Adjusting the motor torqueFor adjusting the motor torque from 1 (minimum) to 5 (maximum). $1/2/3/4/5$	U4	the radio-	 ▲ When you select a radio coding, all saved transmitter are automatically deleted. □□ TWIN's coding lets you save multiple users with the same key (Key block). 		
 A1 Motor type A1 Motor type A1 = 400 kg /2 = 600 kg / 3 = 800 kg / 4 = 1000 kg A3 Gate-swing calibration A4 Resetting parameters A4 Resetting parameters A5 Maneuver count A6 Adjusting the motor torque A7 All Section 200 kg / 2 = 600 kg / 3 = 800 kg / 4 = 1000 kg A4 All Section 200 kg / 2 = 600 kg / 3 = 800 kg / 4 = 1000 kg A4 All Section 200 kg / 2 = 600 kg / 3 = 800 kg / 4 = 1000 kg A4 All Section 200 kg / 2 = 600 kg / 3 = 800 kg / 4 = 1000 kg A5 Adjusting the motor torque from 1 (minimum) to 5 (maximum). A6 Adjusting the formula the formula parameters 		nequency ecue	. ,		
A3 Gate-swing calibration Automatic calibration of the gate-leaf swing (see the CALIBRATING SWING paragraph). <i>OFF = Deactivated / ON = Activated</i> A4 Resetting parameters Caution! The default settings are restored and the travel calibration deleted. <i>OFF = Deactivated / ON = Activated</i> A5 Maneuver count For viewing the number of maneuvers made (001 = 100 maneuvers; 010 = 1,000 maneuvers; 100 = 10,000 maneuvers; 999 = 99,900 maneuvers; CSI = maintenance job). A6 Adjusting the motor torque For adjusting the motor torque from 1 (minimum) to 5 (maximum). 1/2/3/4/5	A1	Motor type			
 A3 calibration OFF = Deactivated / ON = Activated A4 Resetting parameters OFF = Deactivated / ON = Activated A4 Resetting parameters OFF = Deactivated / ON = Activated A5 Maneuver count For viewing the number of maneuvers made (001 = 100 maneuvers; 010 = 1,000 maneuvers; 100 = 10,000 maneuvers; 999 = 99,900 maneuvers; CSI = maintenance job). A6 Adjusting the motor torque For 1 (minimum) to 5 (maximum). 1/2/3/4/5 					
 A4 neseting parameters OFF = Deactivated / ON = Activated A5 Maneuver count A6 Adjusting the motor torque A6 For adjusting the for ware used in the motor torque from 1 (minimum) to 5 (maximum). A6 Intervention of the motor torque form 1 (minimum) to 5 (maximum). 	A3		OFF = Deactivated / ON = Activated		
A5Maneuver countmaneuvers; $100 = 10,000$ maneuvers; $999 = 99,900$ maneuvers; $CSI =$ maintenance job).A6Adjusting the motor torqueFor adjusting the motor torque from 1 (minimum) to 5 (maximum). $1/2/3/4/5$	A4	0	-		
A6 motor torque $1/2/3/4/5$	A5 maneuvers; $100 = 10,000$ maneuvers; $999 = 99,900$ maneuvers		maneuvers; <i>100</i> = 10,000 maneuvers; <i>999</i> = 99,900 maneuvers; <i>CSI</i> = maintenance		
H1 Version View the firmware version.	A6	Adjusting the For adjusting the motor torque from 1 (minimum) to 5 (maximum).			
	H1	Version	View the firmware version.		

COMMISSIONING

Once the electrical connections are done, have only skilled, qualified staff commission the operator into service. Before continuing, make sure the area is free of any obstructions, and that there are mechanical, opening and closing gate stops in place.

Power up and begin configuring the system. **Important!** Start programming by first doing the following functions: F54 (opening direction) and F1 (Total Stop). Once the programming is done, verify that the operator and all the accessories are working properly. Use the < > keys to open and close the gate and ESC to stop it.

 \triangle After powering up the system, the first maneuver is always the opening. In this phase, the gate cannot be closed. You will need to wait for the gate to completely open.

△ Immediately press the STOP button if any suspicious malfunctions, noises or vibrations occur in the system.

MANAGING USERS

A When adding and deleting users, the flashing numbers appearing are those numbers that are available and usable to assign to a new user (max. 250 users).

Before registering the users, make sure the AF radio card is plugged into the connector (see the paragraph called CONTROL DEVICES).

ENTERING A USER WITH AN ASSOCIATED COMMAND

Select U 1. Press ENTER to confirm.

Select a command to associate to the user: The commands are:

- **1** = step-step (open-close);

- 2 = - sequential (open-stop-close-stop);

-3 =only open;

- $\mathbf{4} = \text{partial opening/pedestrian}$.

Press ENTER to confirm...

... a number between 1 and 250 will start flashing for a few seconds. Send the code from the transmitter or other control device, such as, a keypad selector or a transponder.

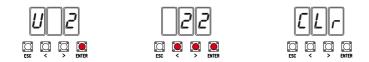
Dote down the user entered into the LIST OF REGISTERED USERS.



DELETING A SINGLE USER

Select U 2. Press ENTER. Activate the function and press ENTER to confirm Use the arrow keys select the number of the user you wish to delete. Press ENTER to confirm...

... CLr will appear on the screen to confirm deletion.



GATE-SWING CALIBRATION

Before calibrating the gate travel, position the gate half-way, check that the maneuvering area is clear of any obstruction and check that there are mechanical opening and closing stops.

 \triangle The mechanical gate-stops are obligatory.

Important! When calibrating, all safety devices will be disabled excluding the one for TOTAL STOP which is active on on the ESC button.

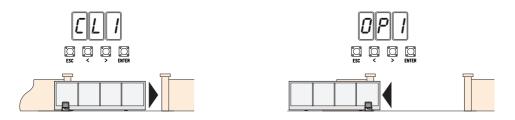
Select A 3. Press ENTER to confirm.

Select 1 and press ENTER to confirm the travel calibration operation.



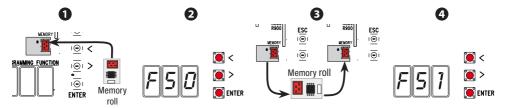


The gate will perform a closing maneuver until it reaches a final stop... ...then the gate will perform an opening maneuver until it reaches a final stop.



SAVING AND UPLOADING ALL DATA (USERS AND CONFIGURATION) WITH THE MEMORY ROLL

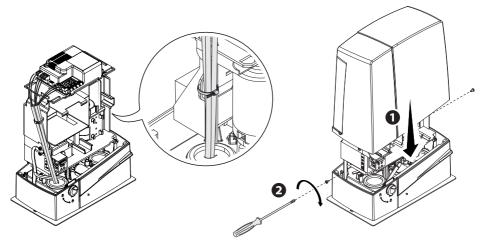
Procedure for memorizing all of the system's user and configuration data by using the Memory Roll, so they can be used with another control board, even on another system. Caution! Fitting and extracting the Memory Roll must be done with the mains power disconnected. Fit the Memory Roll into the its corresponding connector on the control board. **1** Select **F50** and press ENTER to confirm the saving of data in the Memory Roll. **2** Extract the Memory roll and fit it into the connector of another control board. **3** Select **F51** and press ENTER to confirm the uploading of data into the Memory Roll. **4 1** After memorizing the data, it is best to remove the Memory roll.



FINAL OPERATIONS

Once the electrical connections are done and the set up is finished, fasten the cables to the gearmotor jumper using a cable tie.

Fit the cover and fasten it to the sides using the screws.



ERROR MESSAGE

 \square The error messages appear on the display.

E 1	The travel calibration was interrupted when the STOP button was activated
E 2	Gate-leaf travel calibration incomplete
E 3	Encoder broken
E 4	Services test error
E 7	Insufficient operating time
E 9	Closing obstruction
E 10	Opening obstruction
E 11	Maximum number of detected obstructions
E 13	The NC contacts are open (for example, the limit-switches)
E 14	Serial communication error
E 17	Wireless system error
E 18	The wireless system configuration is missing

PAIRED OPERATION

Electrical wiring

Important! Start by performing the following procedures on both operators:

- plugthe RSE card into the connector on the control panel of both operators;

Connect the two control panels to a CAT 5-type (max. 1,000 m) cable onto terminals A-A / B-B / GND-GND, see the PAIRED OPERATION paragraph;

- connect all of the control and safety devices on the MASTER operator's control panel.

Saving users

Execute the procedure, to add a user with an associated command, on the MASTER panel.

Programming

Start by performing the following settings only on the MASTER control panel:

- select 1 (paired mode) from the F49 function and press ENTER to confirm;
- select the opening direction from the F54 function and press ENTER to confirm;
- select ON from the F52 function and press ENTER to confirm the transferring of the parameters to paired mode.

Proceed with the next settings and adjustments only on the MASTER control panel. $\overbrace{}^{\sim}$

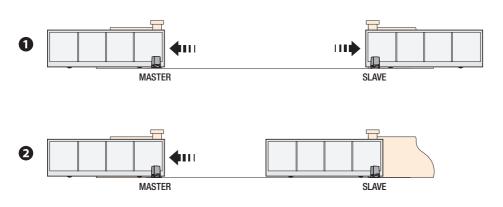
I The programming keys on the SLAVE control panel are disabled.

Operating modes

• Either STEP-STEP or ONLY OPEN command. Both leaves open.

❷PARTIAL/PEDESTRIAN OPENING command. Only the MASTER operator's leaf opens.

For the types of command that can be selected and paired to users, see the ENTERING USERS WITH ASSOCIATED COMMANDS.



WHAT TO DO IF					
ISSUES	POSSIBLE CAUSES	POSSIBLE FIXES			
It neither opens nor closes	Power supply is missing The gear motor is stuck The transmitter emits a weak signal or no signal Control buttons or selectors stuck The wireless accessory does not communicate	Check main power supply Lock the gearmotor Replace the batteries Check integrity of devices and/ or of electrical cables Call for assistance			
The gate opens but does not close	• The photocells are working	• Check that there are no ob- structions in the photocells' area of operation			

 \triangle If the problem cannot be solved by following the fixes in the table or if any malfunctions, anomalies, noises, vibrations or suspicious and unexpected behavior is experienced on the system, call for qualified assistance.

DISMANTLING AND DISPOSAL

☞ CAME S.p.A. applies a certified Environmental Management System at its premises, which is compliant with the UNI EN ISO 14001 standard to ensure the environment is safeguarded.

Please continue safeguarding the environment. At CAME we consider it one of the fundamentals of our operating and market strategies. Simply follow these brief disposal guidelines:

DISPOSING OF THE PACKAGING

The packaging materials (cardboard, plastic, and so on) should be disposed of as solid household waste, and simply separated from other waste for recycling.

Always make sure you comply with local laws before dismantling and disposing of the product.

DISPOSE OF RESPONSIBLY!

DISMANTLING AND DISPOSAL

Our products are made of various materials. Most of these (aluminum, plastic, iron, electrical cables) are classified as solid household waste. They can be recycled by separating them before dumping at authorized city plants.

Whereas other components (control boards, batteries, transmitters, and so on) may contain hazardous pollutants.

These must therefore be disposed of by authorized, certified professional services.

Before disposing, it is always advisable to check with the specific laws that apply in your area. DISPOSE OF RESPONSIBLY!

LIST OF REGISTERED USERS

1	32	63
2	33	64
3	34	65
4	35	66
5	36	67
6	37	68
7	38	69
8	39	70
9	40	71
10	41	72
11	42	73
12	43	74
13	44	75
14	45	76
15	46	77
16	47	78
17	48	79
18	49	80
19	50	81
20	51	82
21	52	83
22	53	84
23	54	85
24	55	86
25	56	87
26	57	88
27	58	89
28	59	90
29	60	91
30	61	92
31	62	93

94	+	126	158	
95	5	127	159	
96	3	128	160	
97	7	129	161	
98	3	130	162	
99)	131	163	
10	0	132	164	
10	1	133	165	
10	2	134	166	
10	3	135	167	
10	4	136	168	
10	5	137	169	
10	6	138	170	
10	7	139	171	
10	8	140	172	
10	9	141	173	
11	0	142	174	
11	1	143	175	
11	2	144	176	
11	3	145	177	
11	4	146	178	
11	5	147	179	
11	6	148	180	
11	7	149	181	
11	8	150	182	
11	9	151	183	
12	0	152	184	
12	1	153	185	
12	2	154	186	
12	3	155	187	
12	4	156	188	
12	5	157	189	

190	222	
191	223	
192	224	
193	225	
194	226	
195	227	
196	228	
197	229	
198	230	
199	231	
200	232	
201	233	
202	234	
203	235	
204	236	
205	237	
206	238	
207	239	
208	240	
209	241	
210	242	
211	243	
212	244	
213	245	
214	246	
215	247	
216	248	
217	249	
218	250	
219		1
220		
221		

Fabbricante / Manufacturer / Hersteller / Fabricant / Fabricante / Fabricante / Wytwórca / Fabrikant

Came S.p.a.



indirizzo / address / adresse / adresse / dirección / endereço / adres / adres Via Martiri della Libertà 15 - 31030 Dosson di Casier, Treviso - Italy

DICHIARA CHE LE AUTOMAZIONI PER CANCELLI SCORREVOLI / DECLARES THAT THE DRIVES FOR SLIDING GATES / ERICLÄRT DASS DIE AUTOMATISIERUNGEN FÜR SCHREBETORE / DECLARE QUE LES AUTOMATISATIONS POUR PORTALIS COULISSANTS / DECLARA QUE LAS AUTOMATIZACIONES PARA PUERTAS CORREDERAS / DECLARA QUE AS AUTOMATIZACIÓS PARA PORTÕES DE CORRER / OSWIADCZA ZE AUTOMATYKA DO BRAM PRZESUWNYCH / VERKLART DAT DE AUTOMATISERING VOOR SCHUIPHEKKEN

BXV04AGS ; BXV06AGS BXV08AGS ; BXV10AGS BXV04RGS ; BXV06RGS BXV08RGS ; BXV10RGS BXV04AGM

SONO CONFORMI ALLE DISPOSIZIONI DELLE SEGUENTI DIRETTIVE / THEY COMPLY WITH THE PROVISIONS OF THE FOLLOW-ING DIRECTIVES / DEN VORGABEN DER FOLGENDEN RICHTLINEN ENTSPRECHEN / SONT CONFORMES AUX DISPOSITIONS DES DIRECTIVES SULVANTES / CUMPLEN CON LAS DISPOSITIONS DE LAS SIGUIENTES DIRECTIVAS / SETÃO DE ACORDO COM AS DISPOSITIONES AUX DEVORSCHEITEN VAN DE VOLGENDE RICHTLUNEN; EUROPEJSKICH / VOLDOEN AAN DE VOORSCHEITEN VAN DE VOLGENDE RICHTLUNEN;

COMPATIBILITA' ELETTROMAGNETICA / ELECTROMAGNETIC COMPATIBILITY / ELEKTROMAGNETISCHE
 VERTRÄGLICHKEIT / ÇOMPATIBILITÉ ÉLECTROMAGNÉTIQUE / COMPATIBILIDAD ELECTROMAGNÉTICA / COMPATIBILIDAD ELECTROMAGNÉTICA / COMPATIBILIDAD ELEKTROMAGNÉTICA / KOMPATYBILNOŚCI ELEKTROMAGNETYCZNEJ / ELEKTROMAGNETISCHE COMPATIBILITEIT : 2014/30/UE.

Riferimento norme armonizzate ed altre norme tecniche / Refer to European regulations and other technical regulations / Harmonisierte Bezugsnormen und andere technische Vorgaben / Référence aux normes

Bezugsnormen und andere technische Vorgaben / Référence aux normes harmonisées et aux autres normes techniques / Referencia normas armonizadas y otras normas técnicas / Referência de normas harmonizadas e outras normas técnicas / Odnosen normy ujedindicione i inne normy techniczne / Saharmoniseerde en andere technische normen waarnaar is EN 61000-6-2:2005 EN 61000-6-3:2007+A1:2011 EN 62233:2008 EN 60335-1:2012+A11:2014 EN 60335-2-103:2015

RISPETTANO I REQUISITI ESSENZIALI APPLICATI: / MEET THE APPLICABLE ESSENTIAL. REQUIREMENTS: / DEN WESENTLICHEN ANGEWANDTEN ANFORDERUNGEN ENTSPRECHEN: / RESPECTENT LES CONDITIONS REQUISES NECESSARES APPLIQUEES: / CUMPLEN CON LOS REQUISITOS ESENCIALES APLICADOS: / RESPETTAM O REQUISITOS ESSENCIAIS APLICADOS: / SPELINIAJA FODSTAWOWE WYMAGANE WYRIUNKI: / VOLDOEN AAN DE TOEPASBATE MINIMUM EISEN:

1.1.3; 1.1.5; 1.2.1; 1.2.2; 1.3.2; 1.3.7; 1.3.8.1; 1.4.1; 1.4.2; 1.5.1; 1.5.6; 1.5.8; 1.5.9; 1.5.9; 1.5.13; 1.6.1; 1.6.3; 1.6.4; 1.7.1; 1.7.2; 1.7.4

PERSONA AUTORIZZATA A COSTITUIRE LA DOCUMENTAZIONE TECNICA PERTINENTE / PERSON AUTHORISED TO COMPLE THE RELEVANT TECHNICAL DOCUMENTATION / PERSONA DIE BENCLUMACHTIGT IST, DIE RELEVANTEN TECHNISCHEN UNTERLAGEN ZUSAMMENZUSTELLEN / DOCUMENTATION TECHNICUE SPECIFICUE D'AUTORISATION A CONSTITUIRE DE / PERSONA FACULTADA PARA LA BADRATA LA DOCUMENTACIÓN TECNICA PERTINENTE/ PESSOA AUTORIZADA A CONSTITUIRE DA DOZUMENTACIÓN TECHNICUE PERSINA MUNETATION / DE CONSTITUIRE LA DOCUMENTACIÓN TECHNICZUS.// DEGENE DIE GEMACHTISD IS DE RELEVANTE TECHNISCHE DOCUMENTACIÓN TECHNICZUS.// DEGENE DIE GEMACHTISD IS DE RELEVANTE TECHNISCHE DOCUMENTACIÓN TECHNICZUS.// DEGENE DIE GEMACHTISD IS DE RELEVANTE TECHNISCHE DOCUMENTACIÓN TECHNICZUS.// DEGENE DIE GEMACHTISD IS DE RELEVANTE TECHNISCHE DOCUMENTACIÓN TECHNICZUS.//

CAME S.p.a.

La documentatione tecnica partinente é stata compliata in conformità all'allegato VIB. / The partinent technical documentation has been drawn up in compliance with attached document VIB. / Dia relevante technicahe Documentation wurde anterpretender der Anlage VIB augestati. / La documentation technique spácifique a dé arrente conformément à l'annese IB / La documentación funcio partinente ha dis referanda en cumplimiento con a anaro VIB. / A documentation technique spácifique a dé arrente conformément à l'annese IB / La documentación funcio partinente ha dis referanda en cumplimiento con a anaro VIB. / A documentation technical technicate da condo com o anexo VIB. / Octorean dokumentacja technicana zostata aredagowana agodirie az zalacanikiem VIB. / De technicate documentative la cogestatel in overenstemming met de bijage VIB.

CME S.p.a. al impogris a transmittere, in regionalis auto excitate adeguatamenter molitate della autoritati, informaziati pertermiti sulla quasi machine, en Came S.p.A. valloving a day molitate lappositi non the national autorities, unorticates to provide information related to the quasi muchines, and 70e Finns Came S.p.A. veptificitet (in the universe a day molitate) and the molitate autorities and the second autorities and the second autorities and the Finns Came S.p.A. veptificitet (in the universe a day molitate) and the molitate autorities and the second autorities and the se

VIETA / FORBIDS / VERBIETET / INTERDIT / PROHIBE / PROIBE / ZABRANIA SIE / VERBIEDT

Dosson di Casier (TV)

5 Marzo / March / März / Mars / Marzo / Março / Marzec / Maart 2018 Legale Rappresentante / Legal Representative /Gesetzlicher Vertreter / Representant Legal / Representante Legal / Representante Legal / Prawny Przedstawiciel / Juridische Vertegenwoordiger

Paologyenute

Fascicolo tecnico a supporto / Supporting technical dossier / Unterstützung technische Dossier / soutenir dossier technique / apoyo expediente técnico / apoiar dossier técnico / wspieranie dokumentacji technicznej / ordersteunende technische dossier; 801MS-0150

Came S.p.a.

Via Mariiri dalla Liberta, 15 - 31030 Dosson di Casier - Treviso - Italy - Tel. (+39) 0422 4940 - Fax (+39) 0422 4941 info@came.it - www.came.com Cap. Soc. 1.61.00.00,00 - C.F. e P.I. 03481280265 - VAT IT 03481280265 - REA TV 275359 - Reg Imp. TV 03461280265

p. 35 - Manual FA01004-EN - 01/2018 - © CAME S.p.A. - Translated original instructions

The contents of this manual may change, at any time, and without notice.



CAME S.P.A. Via Martiri Della Lih

Via Martiri Della Libertà, 15 31030 Dosson di Casier - Treviso - Italy tel. (+39) 0422 4940 - fax. (+39) 0422 4941